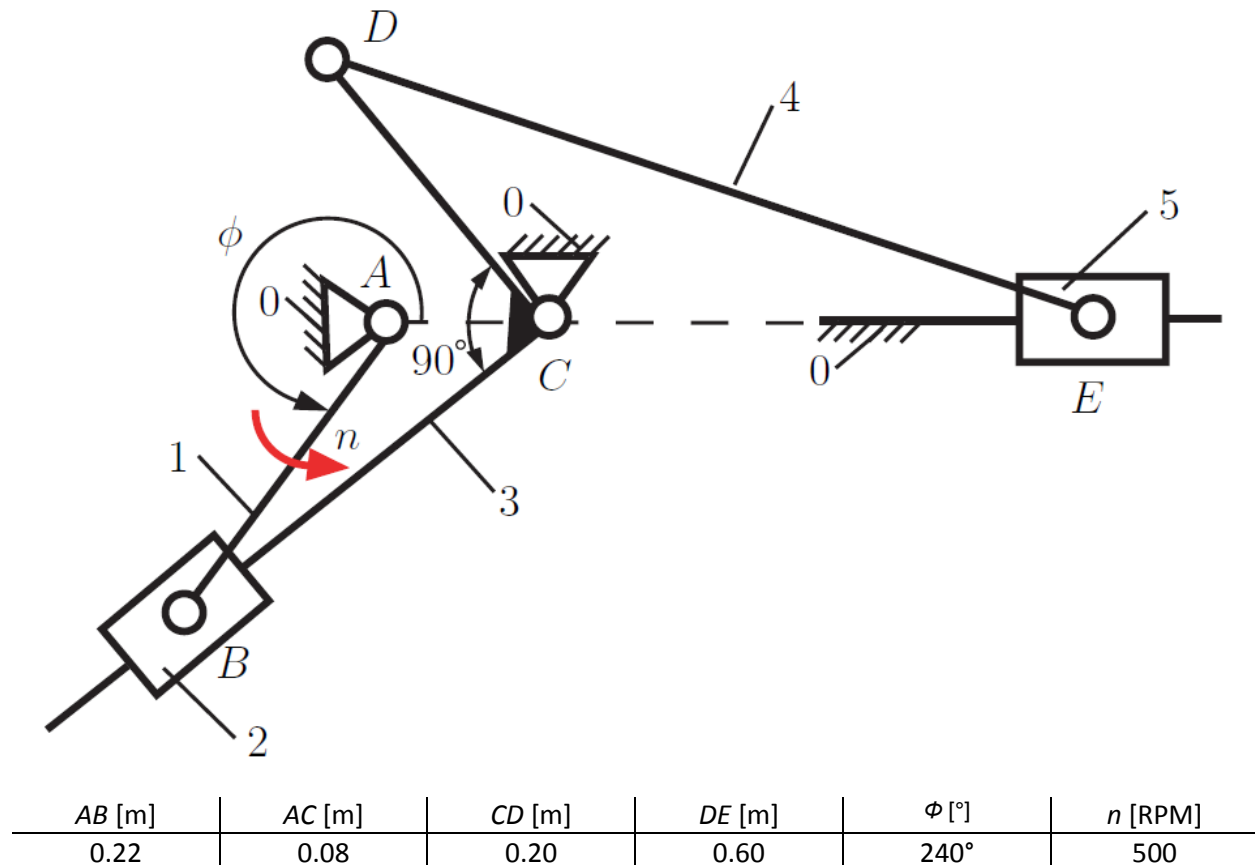


Position Analysis

Ryan Brown – Mechanism 9, Index 1

Due 9/1/2015

Mechanism Details



- Find the positions of the joints and the angles of the links with the horizontal axis when the angle of the driver link 1 with the horizontal axis is ϕ .

- The position of A is considered the origin, so the position of joint A, $\mathbf{A}=[0,0]$.
- The position of B is found using the following equation:

$$\begin{aligned}
 \mathbf{B} &= AB * \cos(\phi) * \bar{i} + AB * \sin(\phi) * \bar{j} \\
 \mathbf{B} &= AB * \cos(240^\circ) * \bar{i} + AB * \sin(240^\circ) * \bar{j} \\
 \mathbf{B} &= -.11 * \bar{i} - .1905 * \bar{j}
 \end{aligned}
 \tag{1}$$

- C is located on the horizontal axis, so the y component of C is 0, and the position of C is $\mathbf{C}=[.08,0]$.

4. The angle of the link between B and C is found using the following equation:

$$\begin{aligned}\angle BC &= \arctan\left(\frac{y_C - y_B}{x_C - x_B}\right) \\ \angle BC &= \arctan\left(\frac{0 - (-.1905)}{.0800 - (-.1100)}\right) \\ \angle BC &= 45 \\ \angle BC &= 45.075 + 180 = 225.075^\circ\end{aligned}\quad (2)$$

5. $\angle BC$ can be used to calculate $\angle CD$ based off the fixed relationship

$$\begin{aligned}\angle CD &= \angle BC - 90^\circ \\ \angle CD &= 225.075^\circ - 90^\circ \\ \angle CD &= 135.075^\circ\end{aligned}\quad (3)$$

6. The position of joint D can be calculated using the following equation

$$\begin{aligned}\mathbf{D} &= CD * \cos(\angle CD) * \bar{i} + CD * \sin(\angle CD) * \bar{j} + \mathbf{C} \\ \mathbf{D} &= .20 * \cos(135.075^\circ) * \bar{i} + .20 * \sin(135.075^\circ) * \bar{j} + .08 * \bar{i} \\ \mathbf{D} &= -.0616 * \bar{i} + .1412 * \bar{j}\end{aligned}\quad (4)$$

7. The position of joint E can then be calculated using the Pythagorean Theorem:

$$\begin{aligned}(y_E - y_D)^2 + (x_E - x_D)^2 &= DE^2 \\ (0 - .1412)^2 + (x_E + .0616)^2 &= DE^2 \\ \mathbf{E} &= .5215 * \bar{i}\end{aligned}\quad (5)$$

8. Using the positions, along with equation 2, the rest of the angles with respect to the horizontal can be calculated.

The results of the above calculations give:

Positions		
Joint	X	Y
A	0	0
B	-.1100	-.1905
C	.0800	0
D	-.0616	.1412
E	.5215	0

Angles With Respect to (+) X-axis	
$\angle AB$	240°
$\angle BC$	225.075°
$\angle CD$	135.075°
$\angle DE$	166.388°